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Gen3DSR: Generalizable 3D Scene Reconstruction via Divide and Conquer from a Single View

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Summary

Most single-image scene-level reconstruction methods require 3D supervised end-to-end training and suffer from poor generalization capabilities. We propose a modular system where each module performs well by focusing on specific tasks that are easier to supervise. Our approach is compositional: the scene is *divided* into entities which are reconstructed (conquered) individually and composed into the final 3D scene using the unprojected depth as a layout reference.

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Input Image



DreamGaussian (non-compositional)















Bernhard Egger



Method



HOPE-Image

29.57

30.62

54.82

GT Geometry

Evaluation

	3D-FRONT	
Method	$Chamfer\downarrow$	F-Score \uparrow
InstPIFu	0.119	70.63
BUOL	0.294	37.04
Uni-3D	0.448	32.97
Gen3DSR	0.099	75.33

Table 1: Full scene reconstruction

DreamGaussian

Method

InstPIFu

DreamG

DreamG +

reprojection

Gen3DSR

Input Image

Gen3DSR (ours)

3D-FRONT

0.124

0.207

0.187

0.120

Chamfer \downarrow F-Score \uparrow Chamfer \downarrow F-Score \uparrow

3.038

4.059

1.446

74.14

41.09

49.98

68.82

 Table 2: Foreground instances reconstruction

Real-world results

